

Rotation Invariant Machine Learning for Highly Symmetric Molecular Configurations

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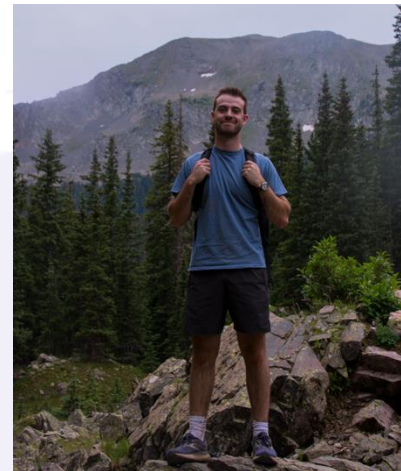
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LA-UR-26-27984

About Me

- Grew up in Alabama
- Graduated from Auburn University in May 2026
 - Bachelor's in Computer Science
 - Minor in Statistics
- Starting a Master's in Computer Science
 - New York University in Fall 2027



Hike at Wheeler Peak in Taos



Hike at Valles Calderas

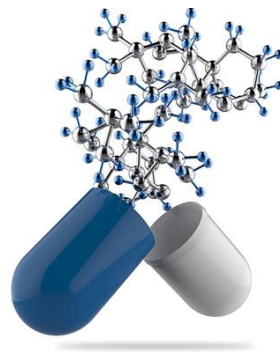


*Proud holder of a
Los Alamos
public library card*



Motivation

- **How can we accurately simulate molecules?**
 - Given a set of atoms, want to predict how they will act
- **Applications:**
 1. Improved drug design
 2. Discovering new materials
 3. Study chemical reactions



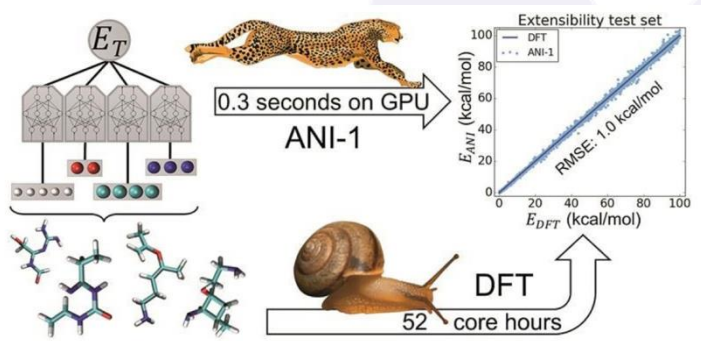
Challenges

1. High quality quantum simulations are **VERY** slow

- Neural networks can approximate quality for orders of magnitude lower cost!

2. Neural networks don't know physics

- If we give models good priors about the physical world, training them becomes much more efficient



Choosing a Good Physical Prior

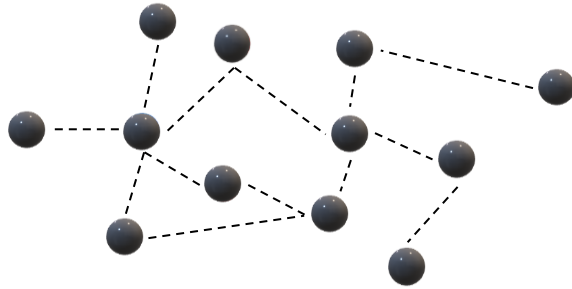
- **By default, neural networks don't understand 3D rotation**
 - If you rotate a molecule, the model will not recognize it
 - Want the model to understand that the global rotation is unimportant
- **Rotation Invariance**
 - Representation does NOT change with rotation
 - Improves training efficiency and accuracy
 - $f(g \cdot x) = f(x)$



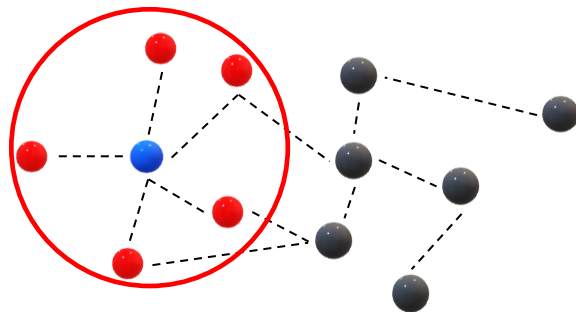
Invariant model image classification is better than the baseline model even with 50x less parameters



Building Invariant Representations



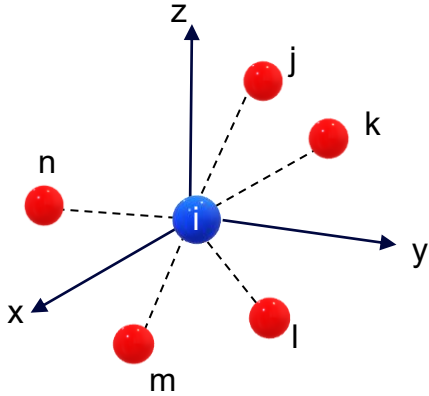
Building Invariant Representations



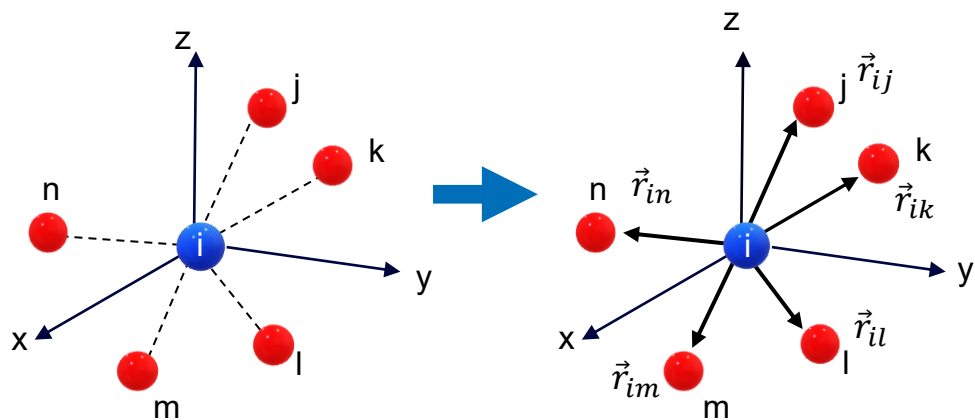
Find Local Neighbors



Building Invariant Representations



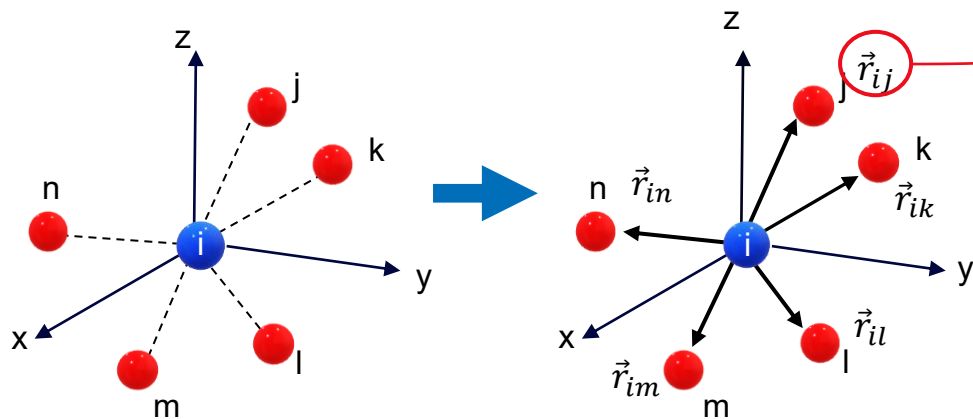
Building Invariant Representations



*Get direction information
of neighbors*



Building Invariant Representations



$$T_{ij}^0(\vec{r}_{ij}), T_{ij}^1(\vec{r}_{ij}), T_{ij}^2(\vec{r}_{ij}), \dots$$

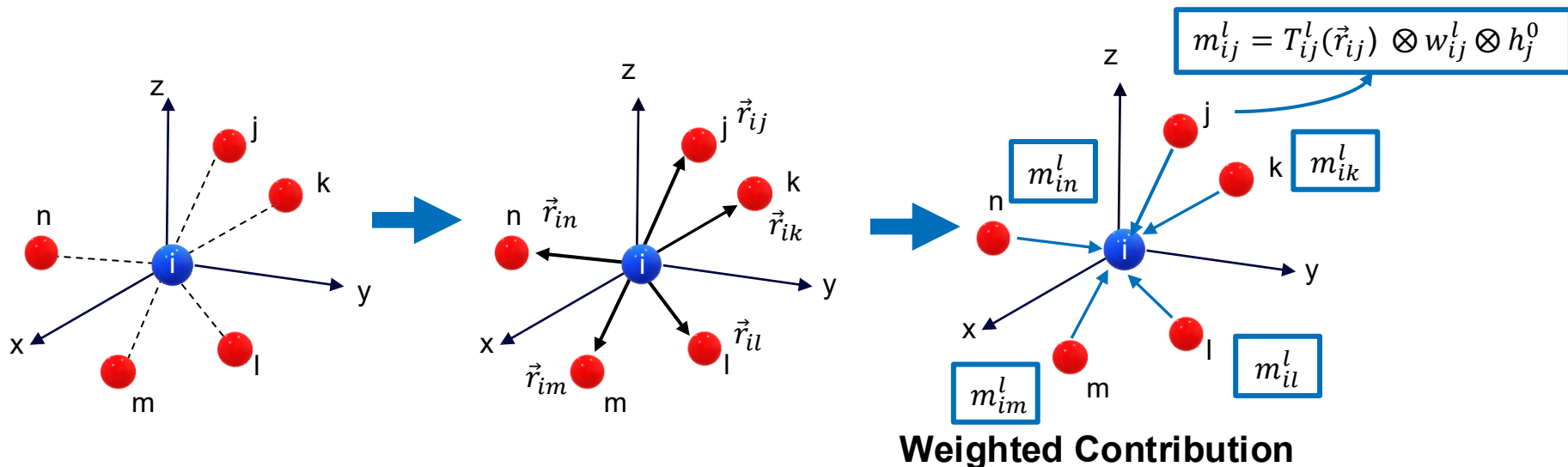
Cartesian Tensors

**How much geometric information
do you want to keep?**

Parameter Value	Information
$L_{\max} = 0$	Only keep distance information
$L_{\max} = 1$	Keep shape information
$L_{\max} = 2$	Keep <i>more</i> shape information - spread of neighbors



Building Invariant Representations



Atom features

Atom type (carbon, hydrogen, etc.) and other existing information

Spatial Information

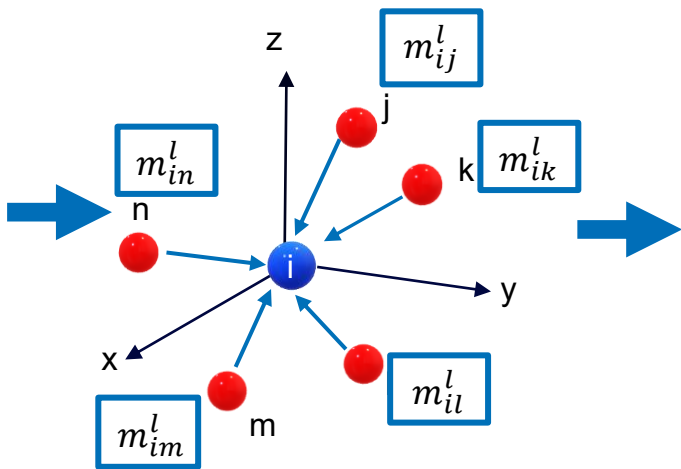
Angles, distances and other high dimensional geometric information

Learnable Weights

w_{ij}^l - learnable weights per atom and tensor type



Building Invariant Representations



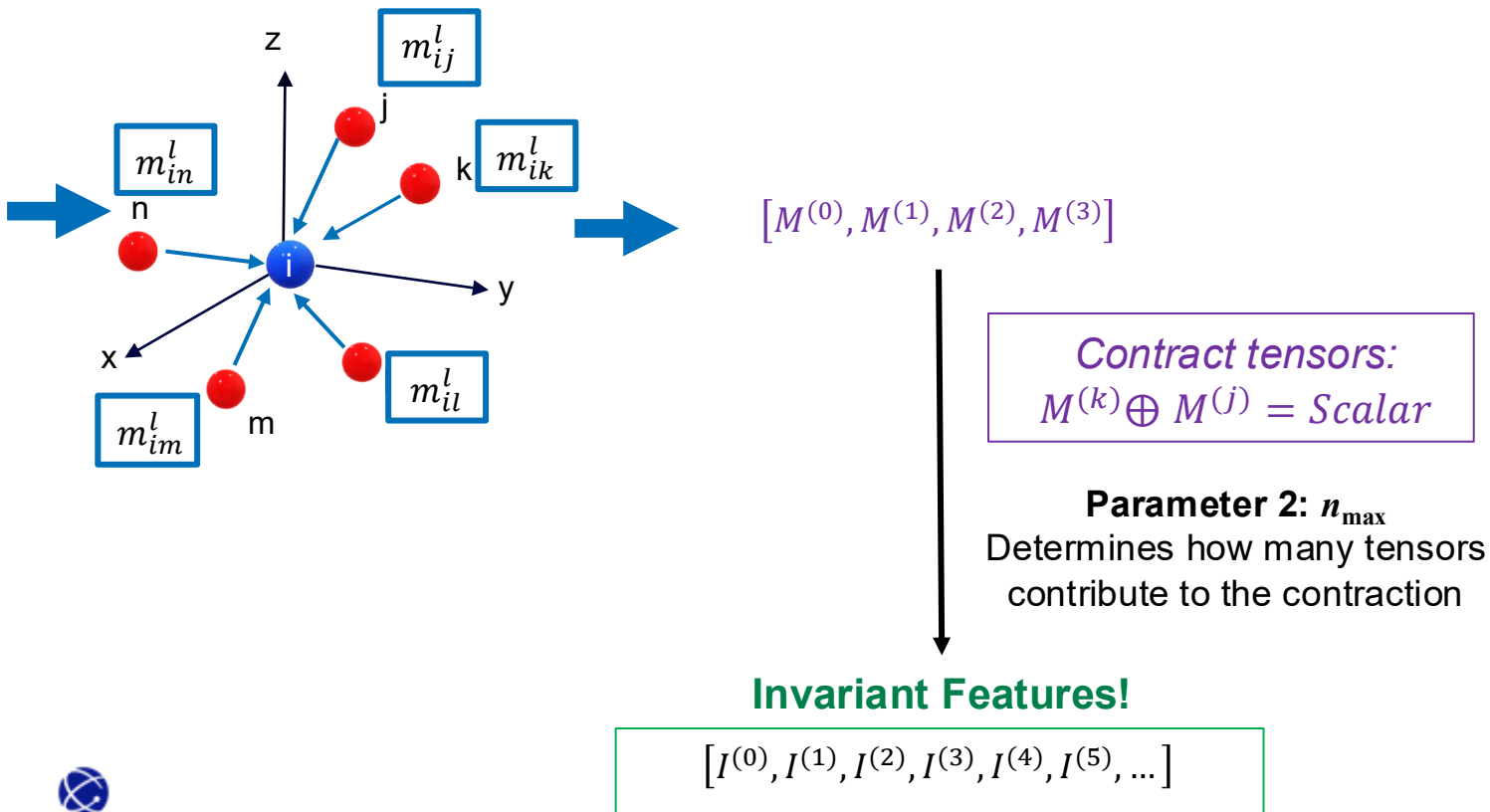
*Combine neighbor
information into center node*

Not Invariant

$$[M^{(0)}, M^{(1)}, M^{(2)}, M^{(3)}]$$



Building Invariant Representations



Tradeoffs in Representation Quality

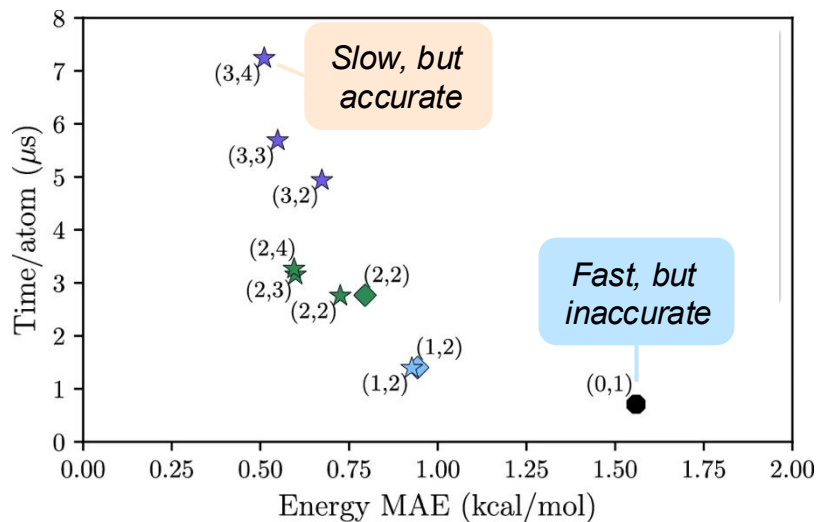
What set (basis) of polynomials is best?:

1. Overly simplified representation

- *Ex: model can see relative distance but not angles*
- Very fast, but high prediction error

2. Extremely detailed representation

- High values for $L_{\max}$ and $n_{\max}$
- Will take months to run



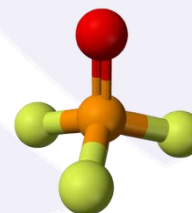
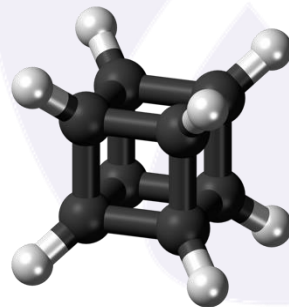
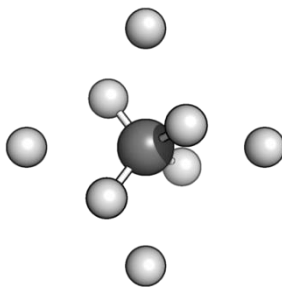
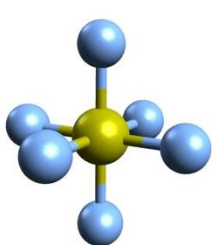
Tradeoffs in Representation Quality

- **Can we get speed AND accuracy?**
 - Basis that gives high amount of detail, but is not slow
- **Where and why do bases fail?**
 - Can we fix those issues with minor changes to latency?



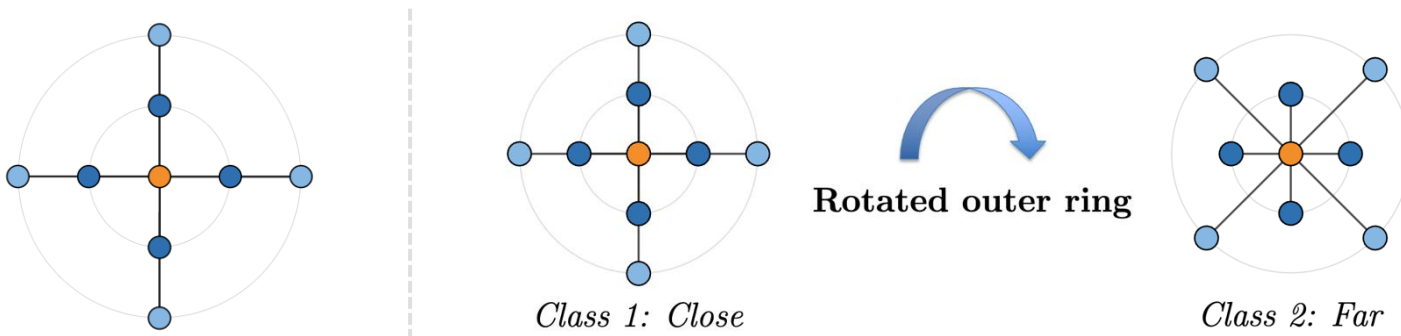
Stress Testing Representation Failures

- Theory tells us that representation should fail to represent symmetrical configurations
- Many molecules in nature have high amounts of symmetry
 - Ex: methane, cubane, sulfur hexafluoride and phosphoryl fluoride
- Want to find out where bases fail with highly symmetrical molecules
 - Need simple benchmark



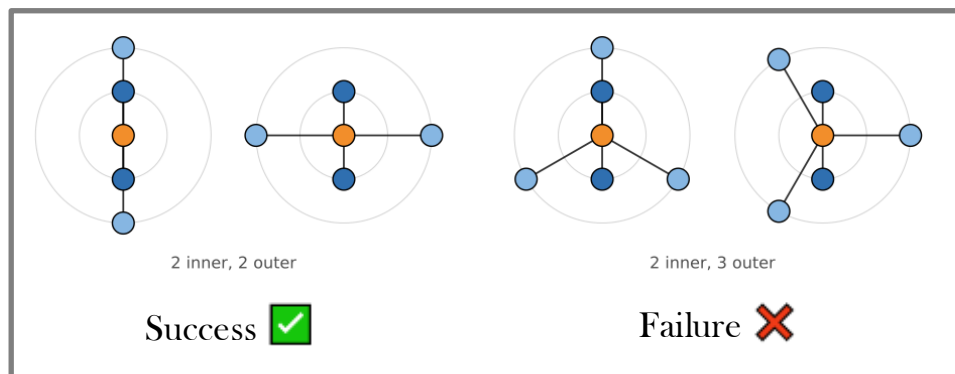
Stress Testing Representation Failures

- **Dataset:**
 - Create n -fold symmetries by rotating two sets of ring around a central node
 - Rings are either close together or far apart
- **Task:**
 - Binary classification
 - Assign the correct close or far labels to the graph



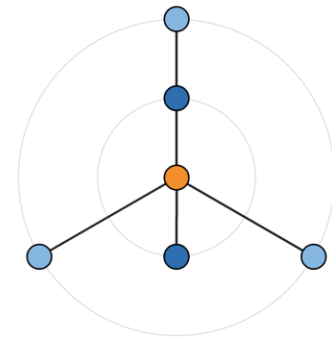
Best basis fails on the majority of the graph pairs

EquiformerV3	1.0	0.5	1.0	0.5	0.5	1.0	0.5	0.5
HIP-HOP ($n_{\max} = 4$)	1.0	0.5	1.0	0.5	0.5	1.0	0.5	0.5
	(1, 3)	(1, 4)	(2, 2)	(2, 3)	(2, 4)	(3, 3)	(3, 4)	(4, 4)
Graph configuration (inner-ring nodes, outer-ring nodes)								



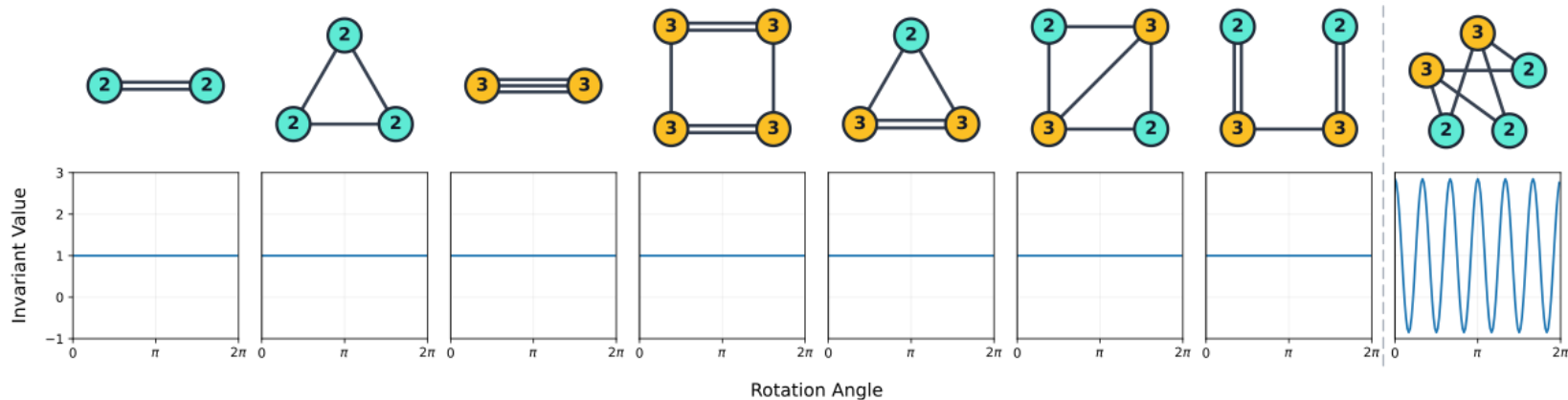
How to Improve the Representation?

- **Current model internals don't change with rotation**
 - Fixed by adding additional contraction that reacts to rotation



Current HIP-HOP basis ($L_{\max}=3$ and $n_{\max}=4$)

New $n_{\max}=5$ contraction



New Basis Reaches Perfect Performance

$\ell_{\max}=3$ Models									
	EquiformerV3	1.0	0.5	1.0	0.5	0.5	1.0	0.5	0.5
<i>Previous Best</i>	HIP-HOP ($n_{\max}=4$)	1.0	0.5	1.0	0.5	0.5	1.0	0.5	0.5
	HIP-HOP ($n_{\max}=4$) + $n_{\max}=5$	1.0	0.5	1.0	1.0	0.5	1.0	0.5	0.5
$\ell_{\max}=4$ Models									
	EquiformerV3	1.0	1.0	1.0	1.0	1.0	1.0	0.5	1.0
	HIP-HOP ($n_{\max}=3$)	1.0	1.0	1.0	1.0	1.0	1.0	0.5	1.0
	HIP-HOP ($n_{\max}=4$)	1.0	1.0	1.0	1.0	1.0	1.0	0.5	1.0
	HIP-HOP ($n_{\max}=4$) + $n_{\max}=7$	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
		(1, 3)	(1, 4)	(2, 2)	(2, 3)	(2, 4)	(3, 3)	(3, 4)	(4, 4)
Graph configuration (inner-ring nodes, outer-ring nodes)									



Increasing Efficiency

- **Why aren't complex bases currently used?**
 - Exponentially more terms to compute → very slow to run
- **Optimized performance around large basis representations**
 - Converted native Python to multi threaded PyTorch
 - Parallelized low level Triton kernels



Increasing Efficiency

Invariant Construction Speed

Basis		Total Construction Time		
$\ell_{\max}$	$n_{\max}$	Baseline	Optimized	Speedup
3	4	0.899 s	0.079 s	11.40×
3	5	1.791 s	0.084 s	21.35×
4	3	0.500 s	0.075 s	6.69×
4	4	4.028 s	0.138 s	29.29×
4	7	267.811 s	0.862 s	310.70×

One time cost during training and inference

Inference Speed

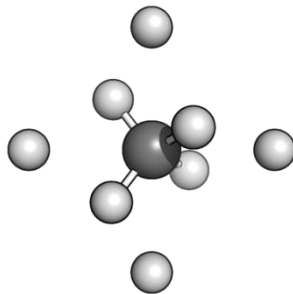
Basis		Time per Atom (μ s)		
$\ell_{\max}$	$n_{\max}$	Baseline	Optimized	Speedup
3	4	7.2	6.9	1.04×
3	5	10.1	10.5	0.96×
4	3	11.9	11.2	1.06×
4	4	28.9	16.5	1.75×
4	7	239.1	113.2	2.11×

How quickly the model can make a prediction



How well do new bases do on real world tasks?

- **Want to accurately predict properties of each molecule**
 1. *Energy*: quantifies the stability of the configuration
 2. *Forces*: direction and strength each atom moves towards lower energy
- **Measure performance on methane dataset**
 - Highly symmetric molecule



Example methane molecule



Methane Results

- Largest basis significantly improves performance
- Complexity of basis does not always improve performance
 - Surprising result!
 - Found cases where theory $\neq$ real life

Basis		Energy		Forces	
$\ell_{\max}$	$n_{\max}$	MAE	RMSE	MAE	RMSE
HIP-HOP-NN					
3	4	0.213 ± 0.016	0.500 ± 0.347	0.607 ± 0.032	2.631 ± 2.557
3	5	0.225 ± 0.031	0.389 ± 0.046	0.642 ± 0.046	3.842 ± 4.498
4	3	0.213 ± 0.004	0.378 ± 0.024	0.623 ± 0.013	1.537 ± 0.333
4	4	0.184 ± 0.003	0.322 ± 0.006	0.551 ± 0.011	1.244 ± 0.026

New
bases



Conclusion

1. Problem:

- 3D representations can fail to represent highly symmetrical configurations

2. Created a benchmark to stress test failures

- Found new bases that succeed on benchmark

3. Optimized model speed and efficiency

- Up to 2x faster

4. Created new model with high accuracy on real world dataset

- 35% lower energy RMSE



What I learned

1. Learned lots of new math

- Group theory, spherical harmonics, etc.

2. Gained experience with low-level optimizations

- Had never done Triton kernel speedups before
- Extremely desirable skill

3. Gained interdisciplinary knowledge

- Only took chemistry 101 in undergrad, learned about computational chemistry and quantum physics

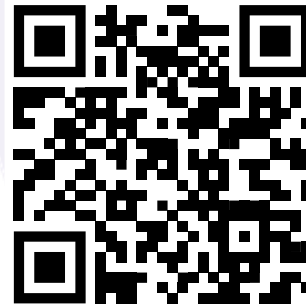


Thank You!

Questions?



Personal Website



HIP-HOP-NN

